



EMBEDDED SYSTEMS

INTRODUCTION

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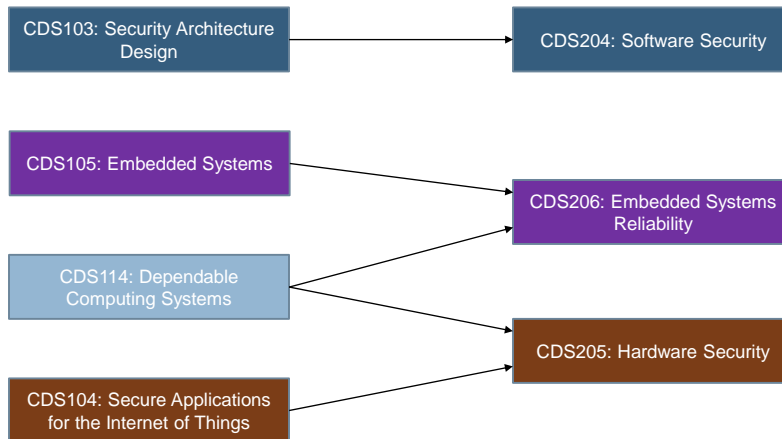
Outline

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- Introduction to Embedded Systems
- Embedded computing platforms (CPUs, FPGAs, ASICs)
 - Course CDS104 (Secure Applications for the Internet of Things): focus on CPUs
 - Course CDS105 (Embedded Systems): focus on FPGAs
- Design embedded systems with FPGAs
 - VHDL Basics (4 lectures)
 - FPGA architecture (1 lecture)
 - FPGA design flow with VHDL (3-4 lab courses)
 - RISC-V processor (2 lab courses)
- Labs: Design, simulation and validation of FPGA designs.
 - Use of EDA tools (Xilinx Vivado) and
 - FPGA development boards (Zybo boards).
- Project: Implementation of an embedded application on FPGA

Role of the course in the track

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What is an embedded system?

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□ Several definitions:

1. "a digital system that provides service as part of a larger system" – G. De Micheli
2. "any device that includes a programmable computer but is not itself a general-purpose computer" – M.Wolf
3. "a less visible computer" - E. Lee
4. "a single-functioned, tightly constrained, reactive computing system" – F. Vahid
5. "a computer system that has a dedicated function within a larger mechanical or electronic system." – Wikipedia

Where are the embedded systems?

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Automotive



reliability



Energy

Medical devices



Industrial applications



Performance



Consumer electronics

Cost

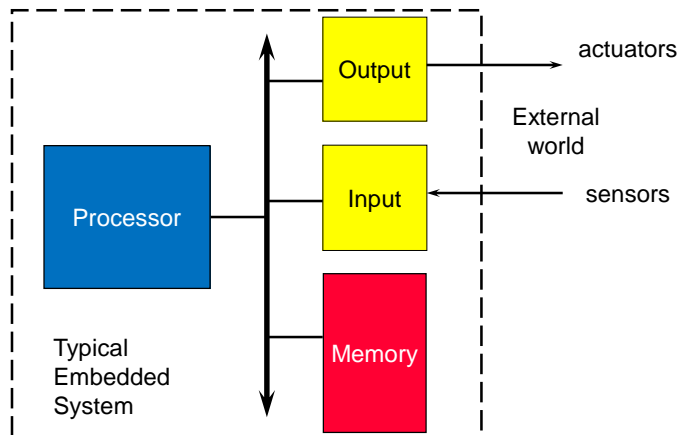


Within the computers



Typical structure

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Embedded processor types

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- Computational microprocessors (32- or 64-bit datapaths)
 - CPU of workstations, PCs, or high-end portable devices (PDAs)
 - x86, PowerPC, SPARC, etc.
- Embedded general purpose microprocessors (32-bit datapaths)
 - Designed for a wide range of embedded applications
 - Often scaled-down version of computational microprocessors
 - ARM, PowerPC, MIPS, x86, 68K, etc.
- Microcontrollers (4-, 8-, or 16-bit datapaths)
 - Integrate processing unit, memory, I/O buses, and peripherals
 - Often low-cost, high-volume devices
- Domain-specific processors (datapath size varies greatly)
 - Designed for a particular application domain
 - Digital signal processors, multimedia processors, graphics processors, network processors, security processors, etc.

Design constraints

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- Small size, low weight
 - Portable devices
 - Transportation applications
- Low power
 - Autonomous for many hours (laptops last only 2-3 hours)
- Harsh environment
 - Heat, vibration, shock
 - Power fluctuations, RF interference
 - Radiation
- Safety-critical operation
 - Must NOT function incorrectly
- Cost sensitivity
 - Small difference in cost adds up over several millions units

Design metrics

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- NRE cost (Non-Recurring Engineering cost):
 - The one-time cost of designing the system
- Unit cost:
 - the cost of manufacturing each copy of the system, excluding NRE cost
- Size:
 - the physical space required by the system
- Performance:
 - the execution time or throughput of the system
- Power:
 - the amount of power consumed by the system
- Flexibility:
 - the ability to change the functionality of the system without incurring heavy NRE cost

Design metrics

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- Time-to-prototype:
 - the time needed to build a working version of the system
- Time-to-market:
 - the time required to develop a system to the point that it can be released and sold to customers
- Dependability
 - Reliability/Availability
 - Safety
 - Security

Real-time operation

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- Correct operation of real-time systems means:
 - Working correctly (functionally correct) but also producing outputs **in time!**
 - i.e., correct result at the right time
- Hard real time: System designed to meet all deadlines
 - A missed deadline is a design flaw
 - Example: ABS brake, nuclear reactor monitoring system
 - System hardware (over) designed for worst-case performance
- Firm real-time: System designed to meet all deadlines, but occasional missed deadline is allowed
 - Example: multimedia systems
 - System hardware designed for average case performance
- Soft real time: System designed to meet as many deadlines as possible
 - Best effort to complete within specified time, but may be late
 - Example: network switch or router
 - System hardware designed for average case performance

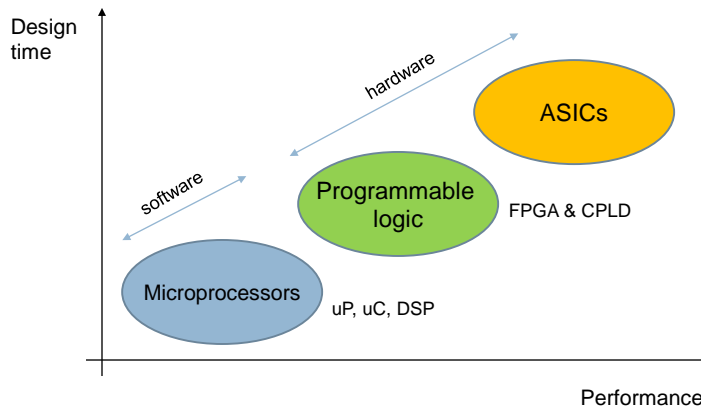
Software vs hardware

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- Many functions can be done by **software** on a general purpose microprocessor OR by **hardware** on an application specific ICs (ASICs)
 - Example: game console graphic, industrial control
 - Leads to Hardware/Software Co-design concept
- Where to place functionality?
 - Dilemma: A Sort algorithm
 - faster in hardware, but more expensive.
 - more flexible in software but slower.
- Must be able to explore these various trade-offs:
 - Cost
 - Speed
 - Reliability
 - Form (size, weight, and power constraints.)

Software vs hardware

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What Are FPGAs

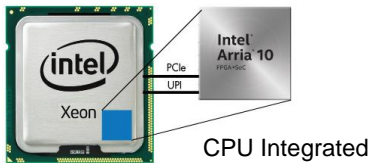
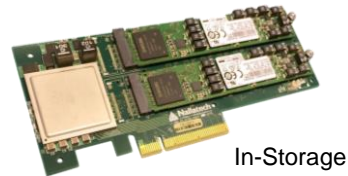
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- **Field-Programmable** Gate Array
- Can be configured to act like any circuit
- Can do many things, but mostly used for acceleration



FPGAs Come In Many Forms

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How Is It Different From CPU/GPUs

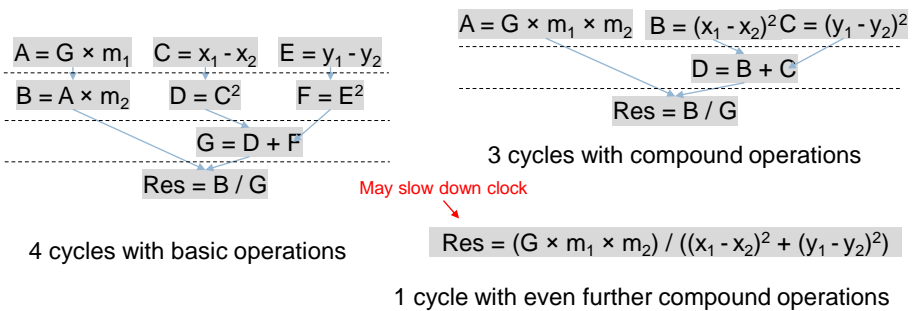
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- GPU – The other major accelerator
- CPU/GPU hardware is fixed
 - “General purpose”
 - we write programs (sequence of instructions) for them
- FPGA hardware is not fixed
 - “Special purpose”
 - Hardware can be whatever we want
 - Will our hardware require/support software? Maybe!
- Optimized hardware is very efficient
 - GPU-level performance
 - 10x power efficiency

Parallel execution in custom hardware

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- Example -- Calculating gravitational force: $\frac{G \times m_1 \times m_2}{(x_1 - x_2)^2 + (y_1 - y_2)^2}$
- 8 instructions on a CPU → 8 cycles**
- Much fewer cycles on a special purpose circuit



How Is It Different From ASICs

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- ASIC (Application-Specific Integrated Circuit)
 - Special chip purpose-built for an application
 - E.g., ASIC bitcoin miner, Intel neural network accelerator
 - Function cannot be changed once expensively built
- + FPGAs can be **field-programmed**
 - Function can be changed completely whenever
 - FPGA fabric **emulates** custom circuits
- - Emulated circuits are not as efficient as bare-metal
 - ~10x performance (larger circuits, faster clock)
 - ~10x power efficiency

